

Rotary clamp cylinder——QCK Series

Compendium of QCK Series



There are magnetic switch slots around the cylinder body convenient to install inducting switch.

Criteria for selection: Cylinder thrust

								U	nit: Ne	wton(N)
Bore	Rod	A ating tuna			Oper	ating pi	essure	(MPa)		
size	size	Acting type	0.1	0.2	0.3	0.4	0.5	0.6	0.7	0.8
12	6	IN(Clamp)	8.5	17.0	25.4	33.9	42.4	50.9	59.4	67.9
12	0	OUT(Release)	11.3	22.6	33.9	45.2	56.5	67.9	79.2	90.4
16	8	IN(Clamp)	15.1	30.2	45.2	60.3	75.4	90.5	105.6	120.6
10	0	OUT(Release)	20.1	40.2	60.3	80.4	100.5	120.6	140.7	160.8
20	12	IN(Clamp)	20.1	40.2	60.3	80.4	100.5	120.6	140.7	160.8
20	12	OUT(Release)	31.4	62.8	94.2	125.7	157.1	188.5	219.9	251.3
25	12	IN(Clamp)	37.8	75.6	113.3	151.1	188.9	226.7	264.4	302.2
25	12	OUT(Release)	49.1	98.2	147.3	196.3	245.4	294.5	343.6	392.7
32	16	IN(Clamp)	60.3	120.6	181.0	241.3	301.6	361.9	422.2	482.5
32	16	OUT(Release)	80.4	160.8	241.3	321.7	402.1	482.5	563.0	643.4
40	16	IN(Clamp)	105.6	211.1	316.7	422.2	527.8	633.3	738.9	844.5
40	16	OUT(Release)	125.7	251.3	377.0	502.7	628.3	754.0	879.6	1005.3
50	20	IN(Clamp)	164.9	329.9	494.8	659.7	824.7	989.6	1154.5	1319.5
30	20	OUT(Release)	196.3	392.7	589.0	785.4	981.7	1178.1	1374.4	1570.8
63	20	IN(Clamp)	280.3	560.6	840.9	1121.2	1401.5	1681.9	1962.2	2242.5
03	20	OUT(Release)	311.7	623.4	935.2	1246.9	1558.6	1870.3	2182.1	2493.8

Installation and application



ACQ series' accessories

- 1. Dirty substances in the pipe must be eliminated before cylinder is connected with pipeline to prevent the entrance of impurities into the cylinder.
- 2. The medium used by cylinder shall be filtered to 40 μ m or below.
- 3. Anti-freezing measure shall be adopted under low temperature environment to prevent moisture freezing.
- 4. If the cylinder is dismantled and stored for a long time, please conduct anti-rust treatment to the surface. Anti-dust jam cap shall be added in air inlet and outlet ports.
- 5. To insure the life-span of cylinder and jig, please use flow control valve to control the speed of cylinder.

QCK Series





Specification

Bore size(mm)	12	16	20	25	32	40	50	63
Acting type				Double	acting			
Fluid		Air	(to be fi	Itered by	40 μ m fil	ter elem	ent)	
Operating pressure		0.	15~1.0	MPa(22~	145psi)(1.5~10ba	ar)	
Proof pressure		1.5MPa(215psi)(15bar)						
Temperature		-20~70℃						
Speed range				50~20	0mm/s			
Rotation angle		90°						
Repeatability				±	2°			
Rotation direction				Turn left o	r turn rig	ıht		
Rotation stroke(mm)	7	.5		9.5	1	5	1	9
Clamping stroke (mm)	10 20		10 20	30		10 20	30 50	
Stroke tolerance				+1.	0			
Cushion type				Bur	nper			
Port size [Note1]		M5:	×0.8		1.	/8"	1,	'4"

[Note1]PT thread, G thread and NPT thread are available.

Add) QCK series are all attached with magnet,

please refer to Page 313 for the specific content of sensor switch.

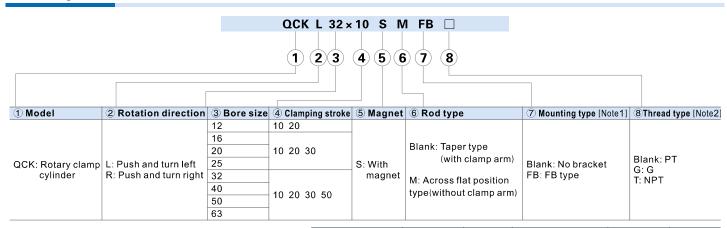
Symbol



Product feature

- 1. It can be used on welding fixfure, the QPQ surface treatment prevent piston rod damage by welding slag; better than chrome plated piston rod.
- The front cover with stainless steel dust scraping ring, can keep the dust and welding slag out, and protect cylinder internal parts.
- 3.The mounting dimension of body is the same as ACQ series, can use ACQ series' accessories.

Ordering code

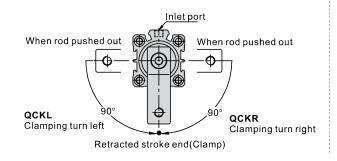


[Note1] Back flange is same as ACQ series (please refer right table), if need front flange, please contact us.

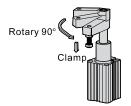
[Note2] When the thread is standard, the code is blank.

Bore size\Accessories	FB	Material	Bore size\Accessories	FB	Material
12	F-ACQ12FA		32	F-ACQ32FA	
16	F-ACQ16FA	Aluminum	40	F-ACQ40FA	Aluminum
20	F-ACQ20FA	alloy	50	F-ACQ50FA	alloy
25	F-ACQ25FA		63	F-ACQ63FA	

The definition of rotation direction and angle

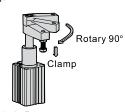


Levorotatory(QCKL):
When the piston of cylinder moves
downward, the swivel arms moves
anticlockwise, this is called
levorotatory.



The order code is L

Dextrorotary(QCKR): When the piston of cylinder moves downward, the swivel arms moves clockwise. this is called dextrorotary.

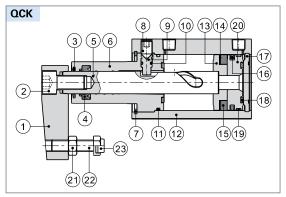


The order code is **R**



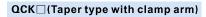
QCK Series

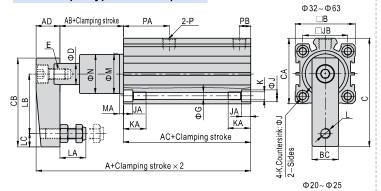
Inner structure and material of major parts



NO.	Item	Material	NO.	Item	Material
1	Rocker	Carbon steel	14	Magnet washer	NBR
2	Screw	Carbon steel			Sintered metal
3	Dust scraping	Νο(Φ12, Φ16)	15	Magnet	(Neodymium-iron-boron(Ф12~Ф25)
3	ring	Stainless steel(Others)			Plastic(Others)
4	Front cover packing	NBR	16	Piston seal	NBR
5	Piston rod	Scr440	17	Back cover	Aluminum alloy
6	Front cover	Aluminum alloy	18	Bumper	TPU(Φ12~Φ25)\NBR(Others)
7	C Clip	Spring steel	19	\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	Νο(Φ12~Φ32)
8	Screw	Carbon steel	19	Wearring	Wear resistant material(Others)
9	Operating screw	SCr440	20	Piston	Brass(Φ12, Φ16)
10	O-ring	NBR			Aluminum alloy(Others)
11	O-ring	NBR	21	Screw	Carbon steel
12	Body	Aluminum alloy	22	Fixing screw	Carbon steel
12	Maanathaldar	Brass(Φ12, Φ16)	23	Bumper	PTFE(Ф12~Ф40)\POM(Others)
13	Magnet holder	Aluminum alloy(Others)			

Dimensions





2-K, Countersink: ΦJ

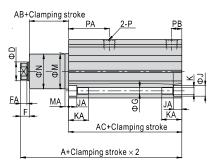
Ф12 Ф16

Bore size\Item	Α	AB	AC	AD	В	ВС	С	CA	СВ	D
12	55	10.5	35.5	9	25	9	36.5	-	29	6
16	59	10.5	35.5	13	29	11	44.5	_	36	8
20	86	8	62	16	36	16	60	-	51	12
25	87	8	63	16	40	16	62	_	51	12
32	108	17.5	71.5	19	45	19	82	49.5	67	16
40	109	25	65	19	53	19	85.5	57	67	16
50	133	31	76.5	25.5	64	25.5	114	71	88	20
63	136	30.5	80	25.5	77	25.5	120.5	84	88	20

Bore size\Item	E	G	J	JA	JB	JC	K
12	$M3 \times 0.5$	3.3	6	3.5	15.5	22	M4 × 0.7
16	$M5 \times 0.8$	3.3	6	3.5	20	28	M4 × 0.7
20	M8 × 1.25	5	9	5.5	25.5	36	M6 × 1.0
25	M8 × 1.25	5	9	5.5	28	40	M6 × 1.0
32	$M10 \times 1.5$	5	9	5.5	34	_	M6 × 1.0
40	M10 × 1.5	5	9	5.5	40	_	M6 × 1.0
50	$M12 \times 1.75$	6.5	10.5	6.5	50	_	M8 × 1.25
63	$M12 \times 1.75$	8.5	14	9	60	_	M10 × 1.5

Bore size\Item	KA	L	LA	LB	LC	М	MA	N	Р	PA	РΒ
12	11	$M4 \times 0.7$	7~13	20	4	11	3	10.8	$\text{M5}\times 0.8$	13.5	5.5
16	11	$M4 \times 0.7$	7~13	25	5	14	3	13.8	$M5 \times 0.8$	15	5.5
20	17	M6 × 1.0	9.5~20.5	35	7	18	3	17.8	$\text{M5}\times 0.8$	30	6
25	17	M6×1.0	9.5~20.5	35	7	23	6	22.5	$M5 \times 0.8$	30	7
32	17	M8 × 1.25	13.5~25.5	45	10	30	7	29.5	1/8"	34.5	8.5
40	17	$M8 \times 1.25$	13.5~25.5	45	10	30	3	29.5	1/8"	26.5	9
50	22	M10 × 1.5	14.5~30	65	10	37	3.5	36.5	1/4"	34	11.5
63	28.5	M10 × 1.5	14.5~30	65	10	48	3.5	47.5	1/4"	34.5	11.5

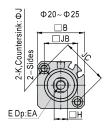
QCK☐M(Across flat position type without clamp arm)



6	4-K, Countersink: ΦJ 2-Sides Parameters of A and A a

Bore size\Item	Α	AB	AC	В	CA	D	F	FA
12	48	9.5	35.5	25	_	6	3	2.5
16	48	9.5	35.5	29	_	8	3	2.5
20	72.5	6.5	62	36	_	12	4	3
25	73.5	6.5	63	40	_	12	4	3
32	93.5	15.5	71.5	45	49.5	16	6.5	5.5
40	94.5	23	65	53	57	16	6.5	5.5
50	112	28	76.5	64	71	20	7.5	5.5
63	115	27.5	80	77	84	20	7.5	5.5

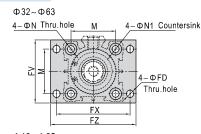
Bore size\Item	Н	E	EΑ	G	J	JA
12	5	$M3 \times 0.5$	6	3.3	6	3.5
16	7	$M5 \times 0.8$	7	3.3	6	3.5
20	10	M8 × 1.25	13	5	9	5.5
25	10	M8 × 1.25	13	5	9	5.5
32	14	M10 × 1.5	15	5	9	5.5
40	14	M10 × 1.5	15	5	9	5.5
50	17	M12 × 1.75	20	6.5	10.5	6.5
63	17	$M12 \times 1.75$	20	8.5	14	9

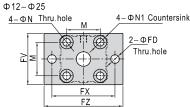


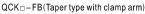
Bore size\Item	JB	JC	K	KA	M	MA	N	Р	PA	PB
12	15.5	22	$M4 \times 0.7$	11	11	3	10.8	$M5 \times 0.8$	13.5	5.5
16	20	28	$M4 \times 0.7$	11	14	3	13.8	$M5 \times 0.8$	15	5.5
20	25.5	36	M6 × 1.0	17	18	3	17.8	$M5 \times 0.8$	30	6
25	28	40	M6 × 1.0	17	23	6	22.5	$M5 \times 0.8$	30	7
32	34	_	M6×1.0	17	30	7	29.5	1/8"	34.5	8.5
40	40	_	M6 × 1.0	17	30	3	29.5	1/8"	26.5	9
50	50	_	M8 × 1.25	22	37	3.5	36.5	1/4"	34	11.5
63	60	_	M10 × 1.5	28.5	48	3.5	47.5	1/4"	34.5	11.5

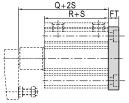
QCK Series

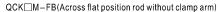
Q□K-FB(With flange)

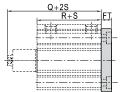








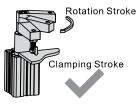




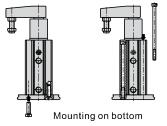
Bore size\Item	R	Q(QCK□)	Q(QCK□M)	М	N	N1	FD	FT	FV	FX	FZ
12	35.5	46	48	15.5	4.5	7.5	4.5	5.5	25	45	55
16	35.5	46	48	20	4.5	7.5	4.5	5.5	30	45	55
20	62	70	72.5	25.5	6.5	10.5	6.5	8	39	48	60
25	63	71	73.5	28	6.5	10.5	6.5	8	42	52	64
32	71.5	89	93.5	34	6.5	10.5	5.5	8	48	56	65
40	65	90	94.5	40	6.5	10.5	5.5	8	54	62	72
50	76.5	107.5	112	50	8.5	13.5	6.5	9	67	76	89
63	80	110.5	115	60	10.5	16.5	9	9	80	92	108

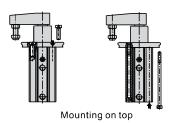
Installation and operation

- 1. To insure the life-span of cylinder and jig, please use flow control valve to control the speed of cylinder.
- 2. The method of installation are mounted by flange on top or bottom.
- 3. Befor the cylinder is connected to pipeline sundries in the pipe must be eliminated, or may cause leakage.
- 4. Please clean the piston-rod and dust scraping ring to protect the cylinder.
- 5. The cylinder using normal magnet ring can use the same sensor as ACQ series. For the cylinder using strong magnet ring we suggest using AirTAC's CS1-69AM sensor.
- 6. Because the rotary force is strong when the cylinder's acting, we suggest using flow control valve to control the speed to protect cylinder.
- 7. Please install the cylinder following the right diagram.
- 8. The installation method as the diagram below is wrong, and will injure the cylinder and shorten the cylinder life.







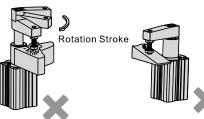


Only can clamping in clamping stroke.



Don't installed horizontally

Don't exert horizontally load or force

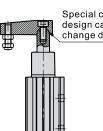




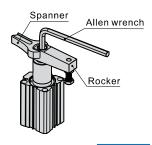


workpiece when clamped

- 9.1) The design of rocker can keep it stable and can change direction by customer.
- 9.2) Please follow the diagram below on right side to assemble/disassemble the rocker by spanner and allen wrench; don't hold the body to assemble/disassemble rocker, or will damage the cylinder.
- 9.3) If need customize rocker, please contact us.



Special conical surface locked design can keep it stable and can change direction by customer.







arm: I

Jig mass :n

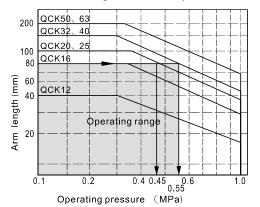
ФΕ

QCK Series

How to select product

- 1. When arms are to be made separately, their length and weight should be within the following range.
- 2. Allowable bending moment:

Use the arm length and operating pressure within graph(1) for allowable bending moment loaded piston rod.

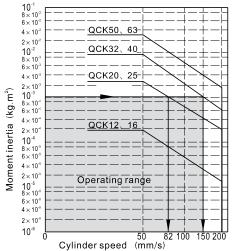


Example: When arm length is 80mm, pressure should be

QCK20/25:0.45MPa QCK32/40:0.55MPa

3. Moment of inertia:

When the arm is long and heavy, damage of internal parts may be caused due to inertia. Use the inertia moment and cylinder speed within graph(2) based on arm requirments.



Example: When arm's moment of inertia is 10⁻³Kg·m², cylinder

speed should be less than QCK20/25:82mm/s QCK32/40:150mm/s

Note) The average speed of piston=the highest speed of piston/1.6

4. Moment of inertia of cylinder's arm when rotating based on its rotary axis, shown in graph(3).

Model	Moment of inertia(Kg·m²)
QCK12	3.555×10^{-6}
QCK16	1.053×10^{-5}
QCK20\25	5.257×10^{-5}
QCK32\40	1.653×10 ⁻⁴
QCK50\63	7.387×10^{-4}

- 5. Calculation reference:
 - 5.1) Moment of inertia of arm (I1): Refer to the graph(3) after he cylinder bore diameter is determined.
 - 5.2) Moment of inertia of jig (I2): According to shape of the jig and the next item 6 "Calculation for moment of inertia", pick out a proper formula for calculation. The jig shown on the right graph is a cylinder , its formula $jig: I_2$ of moment of inertia is:

 $I_2 = (m_2 * D * D)/8 + m_2 * L * L$

When QCK32 is selected: L=0.045m(arm length);

If D = 0.04m $m_2=0.4kg$

From graph(3): $I_1 = 1.653 \times 10^{-4} (\text{Kg} \cdot \text{m}^2)$

By Calculation : $I_2 = (m_2 * D * D)/8 + m_2 * L * L = (0.4 * 0.04 * 0.04)/8 + 0.4 * 0.045 * 0.045$

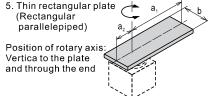
 $=8.9 \times 10^{-4} (Kg \cdot m^2)$

Total value: $I=I_1+I_2=10.553\times 10^{-4}=1.0553\times 10^{-3}(Kg\cdot m^2)$

According to graph(2), the highest speed of the cylinder should be less than 150 mm/s; ranh(1) it can be used under a pressure of 0.9Mpa. The average sp

6.

Diagram	1	Calculation formula of moment of inertia		
1. Thin bar Position of rotary axis: Vertical to the bar and through the end	a, a	$I = \frac{m_1 a_1^2 + m_2 a_2^2}{3}$		
2. Thin bar Position of rotary axis: Vertical to the bar and through the center of gravity		$I = \frac{ma^2}{12}$		
3. Load at the end of lever arm	a ₂ m ₂	$I = m_{1} \times \frac{a_{1}^{2}}{3} + m_{2} \times a_{2}^{2}$ $k = m_{2} \times \frac{2r^{2}}{5}$	+ k	
4. Thin rectangular plate (Rectangular parallelepi Position of rotary axis: Parallel to side b and through the center of gravity	ped) b	$l = \frac{ma^2}{12}$		
5. Thin rectangular plate (Rectangular parallelepiped) a ₂ Position of rotary axis: Vertica to the plate and through the end	a, b	$l=m_1 \times \frac{4a_1^2+b^2}{12}+m_2$	$\times \frac{4a_2^2+b^2}{12}$	



6. Thin rectangular plate (Rectangular parallelepiped

Position of rotary axis: Through the center of gravity and vertical to the plate(Same as also thickrectanglaur plate)



ma2+mb